The R Statistical Computing Environment Basics and Beyond R Programming

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R Programming

Programming Basics

- Function definition
- Control structures:

 Conditionals: if. ifelse. switch • Iteration: for, while, repeat

Recursion

R Programming

Beyond the Basics

Review of MLE of the Binary Logit Model: Estimation by Newton-Raphson

- Choose initial estimates of the regression coefficients, such as $\mathbf{b}_0 = \mathbf{0}$.
- 2 At each iteration t, update the coefficients:

$$\mathbf{b}_t = \mathbf{b}_{t-1} + (\mathbf{X}'\mathbf{V}_{t-1}\mathbf{X})^{-1}\mathbf{X}'(\mathbf{y} - \mathbf{p}_{t-1})$$

where

- X is the model matrix, with x'_i as its *i*th row;
- y is the response vector (containing 0's and 1's);
- $oldsymbol{p}_{t-1}$ is the vector of fitted response probabilities from the previous iteration, the ith entry of which is

$$p_{i,t-1} = \frac{1}{1 + \exp(-\mathbf{x}_i'\mathbf{b}_{t-1})}$$

- V_{t-1} is a diagonal matrix, with diagonal entries $p_{i,t-1}(1-p_{i,t-1})$.
- 3 Step 2 is repeated until \mathbf{b}_t is close enough to \mathbf{b}_{t-1} . The estimated asymptotic covariance matrix of the coefficients is given by $(X'VX)^{-1}$.

Beyond the Basics

Review of MLE of the Binary Logit Model: Estimation by General Optimization

• Another approach is to let a general-purpose optimizer do the work of maximizing the log-likelihood,

$$\log_e L = \sum y_i \log_e p_i + (1 - y_i) \log_e (1 - p_i)$$

- Optimizers work by evaluating the gradient (vector of partial) derivatives) of the 'objective function' (the log-likelihood) at the current estimates of the parameters, iteratively improving the parameter estimates using the information in the gradient; iteration ceases when the gradient is sufficiently close to zero.
- For the logistic-regression model, the gradient of the log-likelihood is

$$\frac{\partial \log_e L}{\partial \mathbf{b}} = \sum (y_i - p_i) \mathbf{x}_i$$

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Beyond the Basics

Review of MLE of the Binary Logit Model: Estimation by General Optimization

• The covariance matrix of the coefficients is the inverse of the matrix of second derivatives. The matrix of second derivatives, called the *Hessian*, is

$$\frac{\partial \log_e L}{\partial \mathbf{h} \partial \mathbf{h}'} = \mathbf{X}' \mathbf{V} \mathbf{X}$$

• The optim function in R, however, calculates the Hessian numerically (rather than using an analytic formula).

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Debugging and Profiling R Code

- Tools integrated with the RStudio IDE:
 - Locating an error: traceback()
 - Setting a breakpoint and examining the local environment of an executing function: browser()
 - A simple interactive debugger: debug()
 - A post-mortem debugger: debugger()
- Measuring time and memory usage with system.time and Rprof

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Object-Oriented Programming

The S3 Object System

- S3 versus S4 objects
- How the S3 object system works
- Method dispatch, for object of class "class": generic(object)
 ⇒ generic.class(object) ⇒ generic.default(object)
 - For example, summarizing an object mod of class "lm": summary(mod)
 summary.lm(mod)
- Objects can have more than one class, in which case the first applicable method is used.
 - For example, objects produced by glm() are of class c("glm", "lm")
 and therefore can inherit methods from class "lm".
- Generic functions: generic <- function(object, other-arguments, ...) UseMethod("generic")
 - For example, summary <- function(object, ...)
 UseMethod("summary")

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