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Notes

Generalized Linear Models

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1. Topics

- ► The structure of generalized linear models
- ▶ Poisson and other generalized linear models for count data
- ► Diagnostics for generalized linear models (as time permits)
- ► Logit and Loglinear models for contingency tables (as time permits)
- ► Implementation of generalized linear models in R

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2.	ed Linear Models The Structure of Generalized Linea dels	2 ar

- A synthesis due to Nelder and Wedderburn, generalized linear models (GLMs) extend the range of application of linear statistical models by accommodating response variables with non-normal conditional distributions.
- Except for the error, the right-hand side of a generalized linear model is essentially the same as for a linear model.

- ► A generalized linear model consists of three components:
- 1. A *random component*, specifying the conditional distribution of the response variable, Y_i , given the explanatory variables.
 - Traditionally, the random component is a member of an "exponential family" — the normal (Gaussian), binomial, Poisson, gamma, or inverse-Gaussian families of distributions — but generalized linear models have been extended beyond the exponential families.
 - The Gaussian and binomial distributions are familiar.
 - Poisson distributions are often used in modeling count data. Poisson random variables take on non-negative integer values, 0, 1, 2, . . . Some examples are shown in Figure 1.

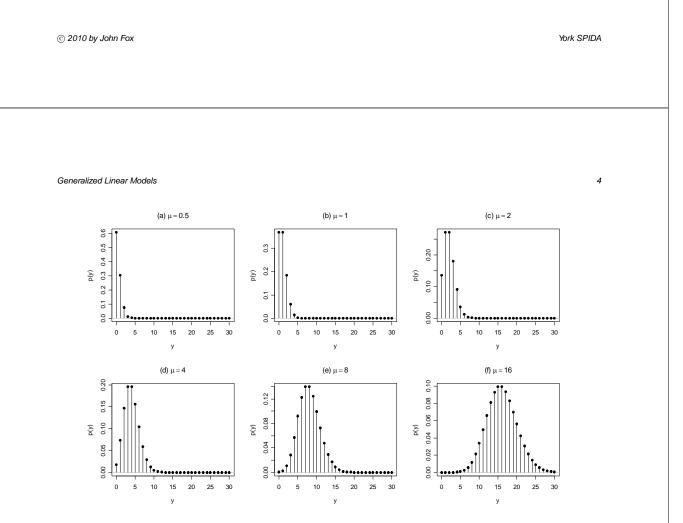


Figure 1. Poisson distributions for various values of the "rate" parameter (mean) μ . © 2010 by John Fox

- The gamma and inverse-Gaussian distributions are for positive continuous data; some examples are given in Figure 2.
- 2. A linear function of the regressors, called the *linear predictor*,

$$\eta_i = \alpha + \beta_1 X_{i1} + \dots + \beta_k X_{ik} = \mathbf{x}'_i \boldsymbol{\beta}$$

on which the expected value μ_i of Y_i depends.

- The *X*'s may include quantitative predictors, but they may also include transformations of predictors, polynomial terms, contrasts generated from factors, interaction regressors, etc.
- 3. An invertible *link function* $g(\mu_i) = \eta_i$, which transforms the expectation of the response to the linear predictor.
 - The inverse of the link function is sometimes called the *mean function*: $g^{-1}(\eta_i) = \mu_i$.

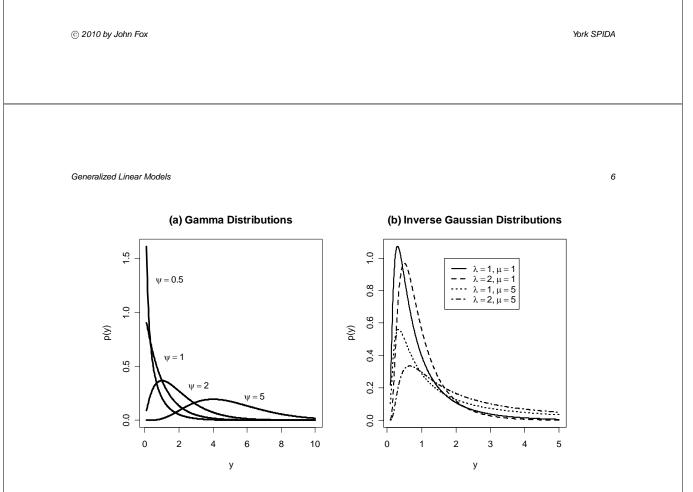


Figure 2. (a) Several gamma distributions for "scale" $\omega = 1$ and various values of the "shape" parameter ψ . (b) Inverse-Gaussian distributions for several combinations of values of the mean μ and "inverse-dispersion" λ .

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• Standard link functions and their inverses are shown in the following table:

Link	$\eta_i = g(\mu_i)$	$\mu_i = g^{-1}(\eta_i)$	
identity	μ_i	η_i	
log	$\log_e \mu_i$	e^{η_i}	
inverse	$\frac{\log_e \mu_i}{\mu_i^{-1}}$	η_i^{-1}	
inverse-square	μ_i^{-2}	$\eta_i^{-1/2}$	
square-root	$\sqrt{\mu_i}$	η_i^2	
logit	$\log_e \frac{\mu_i}{1-\mu_i}$	$\frac{1}{1+e^{-\eta_i}}$	
probit	$\Phi^{-1}(\mu_i)^{\prime}$	$\Phi(\eta_i)$	
log-log	$-\log_e[-\log_e(\mu_i)]$	$\exp[-\exp(-\eta_i)]$	
complementary log-log	$\log_e[-\log_e(1-\mu_i)]$	$1 - \exp[-\exp(\eta_i)]$	

• The logit, probit, and complementary-log-log links are for *binomial data*, where Y_i represents the observed proportion and μ_i the expected proportion of "successes" in n_i binomial trials — that is, μ_i is the probability of a success.

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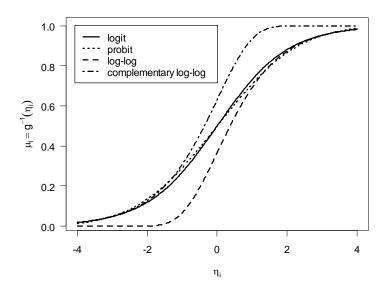
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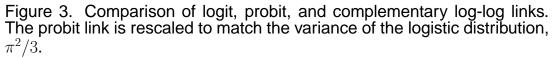
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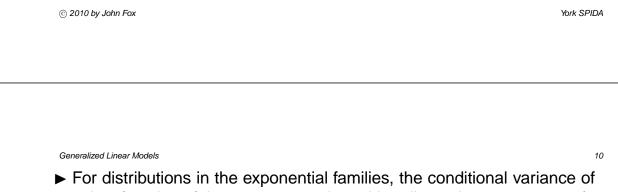
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- \cdot For the probit link, Φ is the standard-normal cumulative distribution function, and Φ^{-1} is the standard-normal quantile function.
- · An important special case is *binary data*, where all of the binomial trials are 1, and therefore all of the observed proportions Y_i are either 0 or 1. This is the case that we examined in the previous session.
- Although the logit and probit links are familiar, the log-log and complementary log-log links for binomial data are not.
 - These links are compared in Figure 3.
 - The log-log or complementary log-log link may be appropriate when the probability of the response as a function of the linear predictor approaches 0 and 1 asymmetrically.

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- For distributions in the exponential families, the conditional variance of Y is a function of the mean μ together with a dispersion parameter ϕ (as shown in the table below).
 - For the binomial and Poisson distributions, the dispersion parameter is fixed to 1.
 - For the Gaussian distribution, the dispersion parameter is the usual error variance, which we previously symbolized by σ_{ε}^2 (and which doesn't depend on μ).

Family	Canonical Link	Range of Y_i	$V(Y_i \eta_i)$
Gaussian	identity	$(-\infty,+\infty)$	ϕ
binomial	logit	$\frac{0, 1, \dots, n_i}{n_i}$	$\frac{\mu_i(1-\mu_i)}{n_i}$
Poisson	log	$0, 1, 2, \dots$	μ_i
gamma	inverse	$(0,\infty)$	$\phi \mu_i^2$
inverse-Gaussian	inverse-square	$(0,\infty)$	$\phi \mu_i^3$

- The canonical link for each familiy is not only the one most commonly used, but also arises naturally from the general formula for distributions in the exponential families.
 - Other links may be more appropriate for the specific problem at hand
 - One of the strengths of the GLM paradigm in contrast, for example, to transformation of the response variable in a linear model — is the separation of the link function from the conditional distribution of the response.
- ► GLMs are typically fit to data by the method of maximum likelihood.
 - Denote the maximum-likelihood estimates of the regression parameters as
 α̂, *β̂*₁, ..., *β̂*_k.
 - · These imply an estimate of the mean of the response, $\hat{\mu}_i = g^{-1}(\hat{\alpha} + \hat{\beta}_1 x_{i1} + \cdots + \hat{\beta}_k x_{ik}).$

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• The log-likelihood for the model, maximized over the regression coefficients, is

$$\log_e L_0 = \sum_{i=1}^n \log_e p(\widehat{\mu}_i, \phi; y_i)$$

where $p(\cdot)$ is the probability or probability-density function corresponding to the family employed.

• A "saturated" model, which dedicates one parameter to each observation, and hence fits the data perfectly, has log-likelihood

$$\log_e L_1 = \sum_{i=1}^n \log_e p(y_i, \phi; y_i)$$

• Twice the difference between these log-likelihoods defines the *residual deviance* under the model, a generalization of the residual sum of squares for linear models:

$$D(\mathbf{y}; \widehat{\boldsymbol{\mu}}) = 2(\log_e L_1 - \log_e L_0)$$

where $\mathbf{y} = \{Y_i\}$ and $\widehat{\boldsymbol{\mu}} = \{\widehat{\mu}_i\}$.

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- Dividing the deviance by the estimated dispersion produces the scaled deviance: D(y; μ)/φ.
- Likelihood-ratio tests can be formulated by taking differences in the residual deviance for nested models.
- For models with an estimated dispersion parameter, one can alternatively use incremental *F*-tests.
- Wald tests for individual coefficients are formulated using the estimated asymptotic standard errors of the coefficients.
- ► Some familiar examples:
 - Combining the identity link with the Gaussian family produces the normal linear model.
 - The maximum-likelihood estimates for this model are the ordinary least-squares estimates.
 - Combining the logit link with the binomial family produces the logisticregression model (linear-logit model).

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• Combining the probit link with the binomial family produces the linear probit model.

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3. Poisson GLMs for Count Data

- Poisson generalized linear models arise in two common formally identical but substantively distinguishable contexts:
- 1. when the response variable in a regression model takes on non-negative integer values, such as a count;
- 2. to analyze associations among categorical variables in a contingency table of counts.
- ► The canonical link for the Poisson family is the log link.

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3.1 Over-Dispersed Binomial and Poisson Models	

- ▶ The binomial and Poisson GLMs fix the dispersion parameter ϕ to 1.
- It is possible to fit versions of these models in which the dispersion is a free parameter, to be estimated along with the coefficients of the linear predictor
 - The resulting error distribution is not an exponential family; the models are fit by "quasi-likelihood."
- ► The regression coefficients are unaffected by allowing dispersion different from 1, but the coefficient standard errors are multiplied by the square-root of $\hat{\phi}$.
 - Because the estimated dispersion typically exceeds 1, this inflates the standard errors
 - That is, failing to account for "over-dispersion" produces misleadingly small standard errors.

- So-called over-dispersed binomial and Poisson models arise in several different circumstances.
 - For example, in modeling proportions, it is possible that
 - · the probability of success μ varies for different individuals who share identical values of the predictors (this is called "unmodeled heterogeneity");
 - \cdot or the individual successes and failures for a "binomial" observation are not independent, as required by the binomial distribution.
- ► The negative-binomial distribution is also frequently used to model over-dispersed count data.

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4. Diagnostics for GLMs

- Most regression diagnostics extend straightforwardly to generalized linear models.
- These extensions typically take advantage of the computation of maximum-likelihood estimates for generalized linear models by iterated weighted least squares (the procedure typically used to fit GLMs).

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4.1 Outlier, Leverage, and Influence Diagnostics

4.1.1 Hat-Values

- Hat-values for a generalized linear model can be taken directly from the final iteration of the IWLS procedure
- ► They have the usual interpretation except that the hat-values in a GLM depend on Y as well as on the configuration of the X's.

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 ► Several kinds of residuals can be defined for generalized linea • Response residuals are simply the differences between the response and its estimated expected value: Y_i - µ̂_i. 	
 Working residuals are the residuals from the final WLS fit. 	

- These may be used to define partial residuals for component-plusresidual plots (see below).
- *Pearson residuals* are case-wise components of the Pearson goodness-of-fit statistic for the model:

$$\frac{\widehat{\phi}^{1/2}(Y_i - \widehat{\mu}_i)}{\sqrt{\widehat{V}(Y_i|\eta_i)}}$$

where ϕ is the dispersion parameter for the model and $V(Y_i|\eta_i)$ is the variance of the response given the linear predictor.

 Standardized Pearson residuals correct for the conditional response variation and for the leverage of the observations:

$$R_{Pi} = \frac{Y_i - \widehat{\mu}_i}{\sqrt{\widehat{V}(Y_i|\eta_i)(1 - h_i)}}$$

- Deviance residuals, D_i , are the square-roots of the case-wise components of the residual deviance, attaching the sign of $Y_i \hat{\mu}_i$.
- Standardized deviance residuals are _

$$R_{Di} = \frac{D_i}{\sqrt{\widehat{\phi}(1-h_i)}}$$

- Several different approximations to studentized residuals have been suggested.
 - To calculate exact studentized residuals would require literally refitting the model deleting each observation in turn, and noting the decline in the deviance.

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• Here is an approximation due to Williams:

$$E_i^* = \sqrt{(1 - h_i)R_{Di}^2 + h_i R_{Pi}^2}$$

where, once again, the sign is taken from $Y_i - \hat{\mu}_i$.

• A Bonferroni outlier test using the standard normal distribution may be based on the largest absolute studentized residual.

4.1.3 Influence Measures

An approximation to Cook's distance influence measure is

$$D_i = \frac{R_{Pi}^2}{\widehat{\phi}(k+1)} \times \frac{h_i}{1 - h_i}$$

- Approximate values of dfbeta_{ij} and dfbetas_{ij} (influence and standardized influence on each coefficient) may be obtained directly from the final iteration of the IWLS procedure.
- There are two largely similar extensions of added-variable plots to generalized linear models, one due to Wang and another to Cook and Weisberg.

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4.2 Nonlinearity Diagnostics

- Component-plus-residual plots also extend straightforwardly to generalized linear models.
 - Nonparametric smoothing of the resulting scatterplots can be important to interpretation, especially in models for binary responses, where the discreteness of the response makes the plots difficult to examine.
 - Similar effects can occur for binomial and Poisson data.
- Component-plus-residual plots use the linearized model from the last step of the IWLS fit.
 - For example, the partial residual for X_j adds the working residual to $B_j X_{ij}$.
 - The component-plus-residual plot graphs the partial residual against X_j .

5. Logit and Loglinear Models for Contingency Tables

5.1 The Binomial Logit Model for Contingency Tables

- When the explanatory variables as well as the response variable — are discrete, the joint sample distribution of the variables defines a contingency table of counts.
- ► An example, drawn from *The American Voter* (Converse et al., 1960), appears below.
 - This table, based on data from a sample survey conducted after the 1956 U.S. presidential election, relates voting turnout in the election to strength of partisan preference, and perceived closeness of the election:

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		Turnout	
Perceived	Intensity of	Voted	Did Not
Closeness	Preference	voieu	Vote
One-Sided	Weak	91	39
	Medium	121	49
	Strong	64	24
Close	Weak	214	87
	Medium	284	76
	Strong	201	25

• The following table gives the *empirical logit* for the response variable,

$$\log_e \frac{\text{proportion voting}}{\text{proportion not voting}}$$

for each of the six combinations of categories of the explanatory variables:

Perceived Closeness	Intensity of Preference	$\log_e \frac{\text{Voted}}{\text{Did Not Vote}}$
One-Sided	Weak	0.847
	Medium	0.904
	Strong	0.981
Close	Weak	0.900
	Medium	1.318
	Strong	2.084

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· For example,

logit(voted|one-sided, weak preference)

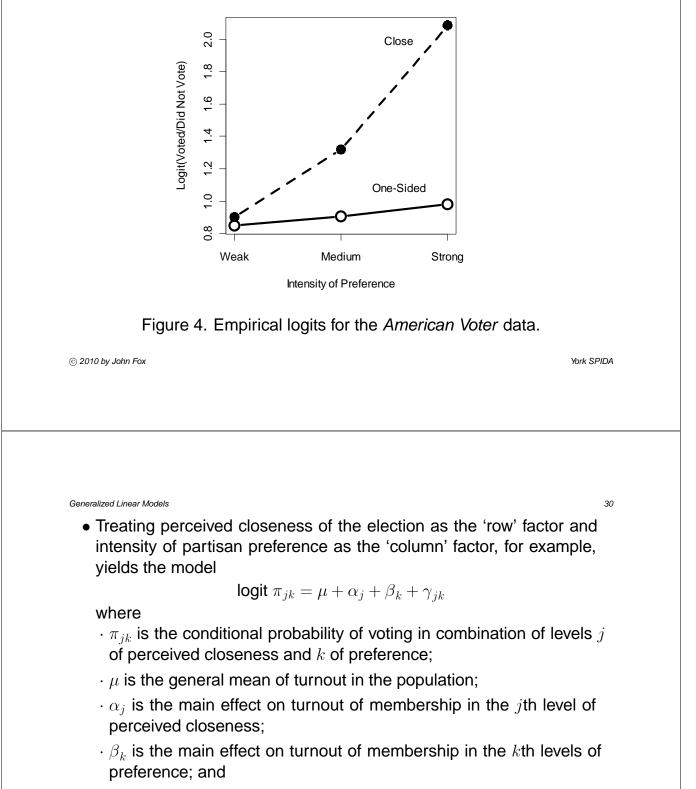
$$= \log_e \frac{91/130}{39/130}$$
$$= \log_e \frac{91}{39}$$
$$= 0.847$$

Because the conditional proportions voting and not voting share the same denominator, the empirical logit can also be written as

$$\log_e \frac{\text{number voting}}{\text{number not voting}}$$

- The empirical logits are graphed in Figure 4, much in the manner of profiles of cell means for a two-way analysis of variance.
- ► Logit models are fully appropriate for tabular data.
 - When, as in the example, the explanatory variables are qualitative or ordinal, it is natural to use logit or probit models that are analogous to analysis-of-variance models.

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 $\cdot \gamma_{jk}$ is the interaction effect on turnout of simultaneous membership in levels *j* of perceived closeness and *k* of preference.

- Under the usual sigma constraints, this model leads to deviation-coded regressors (contr.sum in R), as in the analysis of variance.
- Likelihood-ratio tests for main-effects and interactions can be constructed in close analogy to the incremental *F*-tests for the two-way ANOVA model.

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5.2 Loglinear Models

- Poisson GLMs may also be used to fit loglinear models to a contingency table of frequency counts, where the object is to model association among the variables in the table.
- The variables constituting the classifications of the table are treated as 'explanatory variables' in the Poisson model, while the cell count plays the role of the 'response.'
- We previously examined Campbell et al.'s data on voter turnout in the 1956 U.S. presidential election
 - We used a binomial logit model to analyze a three-way contingency table for turnout by perceived closeness of the election and intensity of partisan preference.
 - The binomial logit model treats turnout as the response.
- An alternative is to construct a log-linear model for the expected cell count.

• This model looks very much like a three-way ANOVA model, where in place of the cell mean we have the log cell expected count:

$$\log \mu_{ijk} = \mu + \alpha_i + \beta_j + \gamma_k + \alpha \beta_{ij} + \alpha \gamma_{ik} + \beta \gamma_{jk} + \alpha \beta \gamma_{ijk}$$

- Here, variable 1 is perceived closeness of the election; variable 2 is intensity of preference; and variable 3 is turnout.
- Although a term such as $\alpha\beta_{ij}$ looks like an 'interaction,' it actually models the association between variables 1 and 2.
- The three-way term $\alpha\beta\gamma_{ijk}$ allows the association between any pair of variables to be different in different categories of the third variable; it thus represents an interaction in the usual sense of that concept.
- ► In fitting the log-linear model to data, we can use sigma-constraints on the parameters, much as we would for an ANOVA model.

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Generalized Linear Models ► In the context of a three-way contingency table, the loglinear mo	³⁴ del
above is a saturated model, because it has as many independe	

The likelihood-ratio test for the three-way term Closeness × Preference × Turnout is identical to the test for the Closeness × Preference interaction in the logit model in which Turnout is the response variable.

parameters (12) as there are cells in the table.

- ► In general, as long as we fit the parameters for the associations among the explanatory variable (here Closeness×Preference and, of course, its lower-order relatives, Closeness and Preference) and for the marginal distribution of the response (Turnout), the loglinear model for a contingency table is equivalent to a logit model.
 - There is, therefore, no real advantage to using a loglinear model in this setting.
 - Loglinear models, however, can be used to model association in other contexts.

6. Implementation of GLMs in R

► The glm() function in R is very similar in use to lm(),

glm(formula, family, data, subset, weights, na.action, contrasts)

- ► The family argument is one of gaussian (the default), binomial, poisson, Gamma, inverse.gaussian, quasi, quasibinomial, or quasipoisson.
 - It is possible to write functions for additional families (e.g., the negative.binomial family for count data in the MASS package).
- The "family-generator" function specified as the value of the family argument can itself take a link argument (and possibly other arguments); in each case there is a default link.
 - The available links for each family (○) and the default link (●) are given in the following table:

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	link			
family	identity	inverse	sqrt	1/mu^2
gaussian	•	0		
binomial				
poisson	0		0	
Gamma	0	•		
inverse.		0		•
gaussian	0	0		•
quasi	•	0	0	0
quasibinomial				
quasipoisson	0		0	

	link			
family	log	logit	probit	cloglog
gaussian	0			
binomial	0	٠	0	0
poisson	•			
Gamma	0			
inverse.	0			
gaussian				
quasi	0	0	0	0
quasibinomial		•	0	0
quasipoisson	•			

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